

6.200 Circuits and Electronics

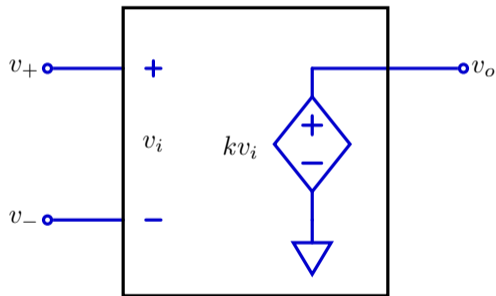
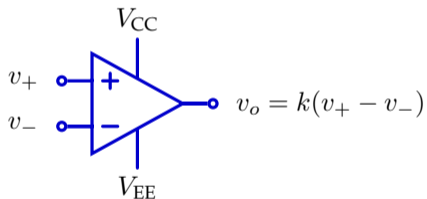
Week 8, Lecture A:
Modularity in Circuits:
Operational Amplifiers

Midterm 1: tonight

PSet 8 releases tonight as well (no hardware, no prelab)

Operational Amplifiers

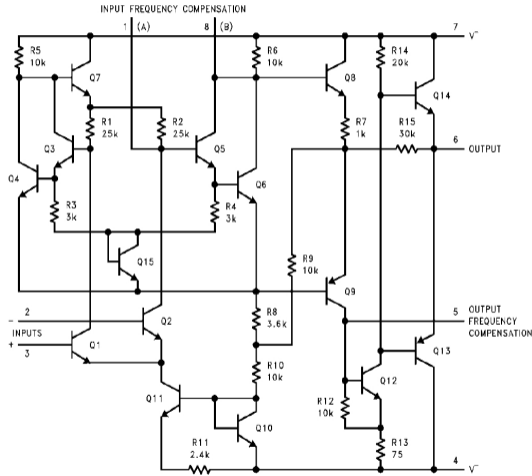
An operational amplifier (“op-amp”) can be modeled* as a voltage-controlled voltage source, where k is intentionally large (typically $\sim 10^5 - 10^7$):



* sometimes

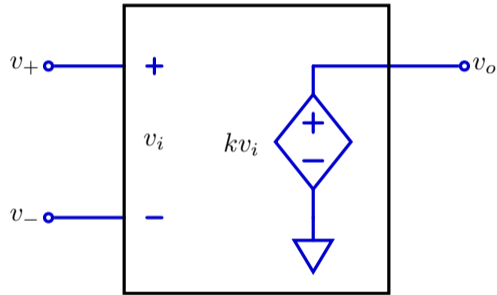
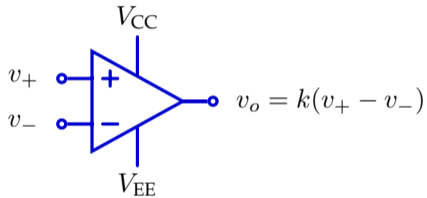
Operational Amplifiers

What's *actually* in an op-amp? Here is a more accurate circuit model of a $\mu A709$ op-amp:



But that's a pain...

Characterizing an Op-amp (VCVS Model)

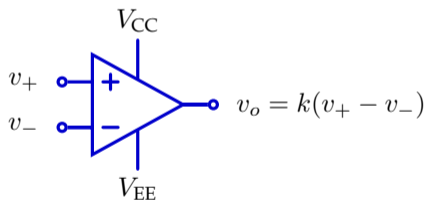


Sketch a graph of v_o versus $(v_+ - v_-)$

Supply Rails

Op-amps derive power from connections to a power supply, and the output voltage is typically constrained by that power supply:

$$V_{EE} < v_o < V_{CC}$$

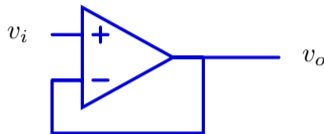


If $k(v_+ - v_-) > V_{CC}$, then v_o will be V_{CC} .

If $k(v_+ - v_-) < V_{EE}$, then v_o will be V_{EE} .

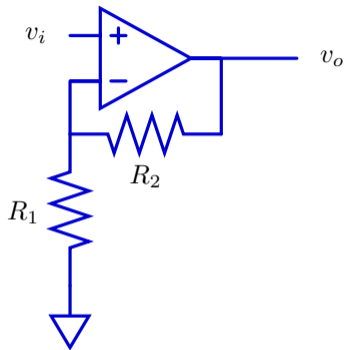
Closing the Loop

Many useful applications of op-amps involve connecting them in *feedback*, where the output affects one of the input terminals. For example, consider the following configuration:



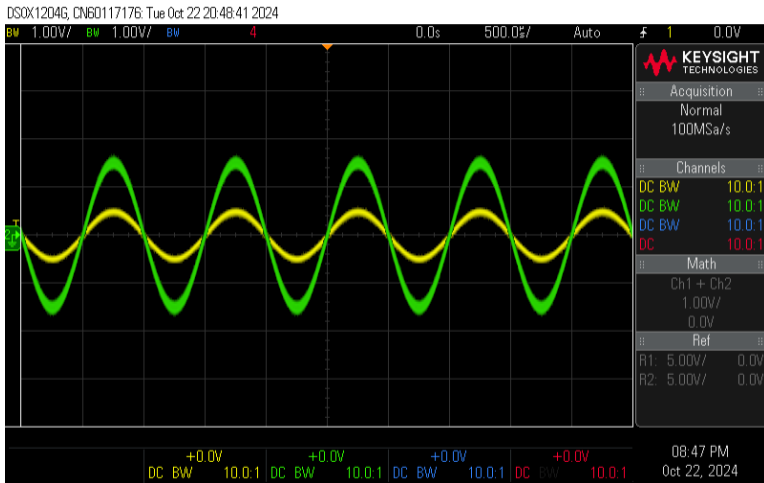
What is v_o (in terms of v_i)? Use the VCVS model from the previous slides.

Another Op-Amp Circuit



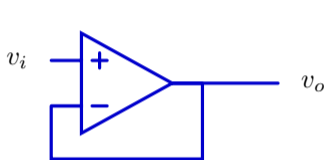
What is v_o (in terms of v_i)? Use the VCVS model from the previous slides.

Hmmmm...

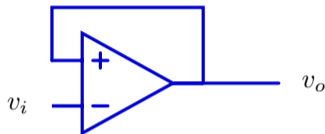


Negative Feedback

Most of the useful circuits we'll see moving forward involve feedback. But the presence of the + and - signs on the inputs imply that something is different between the following:



$$v_o = \frac{k}{1+k} \approx 1$$

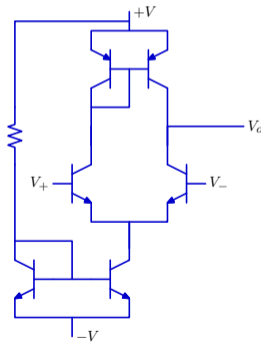


$$v_o = \frac{-k}{1-k} \approx 1$$

But the analysis produces the same answer! The VCVS model alone isn't enough to explain the difference here; we need to go deeper...

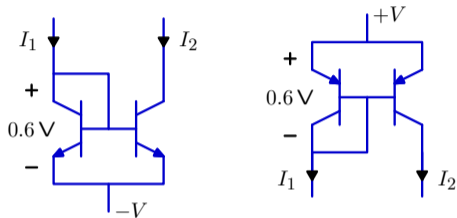
“Thinking” Like an Op-Amp

In fact, both of the systems from the previous page have metastable points at $v_o \approx v_i$. However, in order to understand the difference, we need to think about **temporal dynamics**, and what happens when the system moves away from that metastable point. Let's consider a slightly-more-complicated op-amp model. Let's start with a small op-amp:

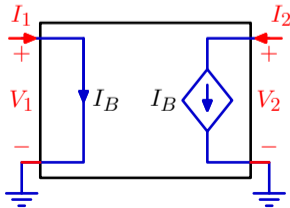


Common Transistor Patterns

A *current mirror* sets its output current to equal its input current.

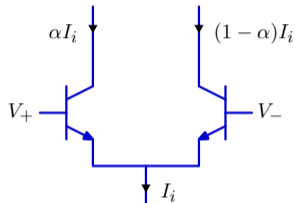


It can be represented by a current-controlled current source:



Common Transistor Patterns

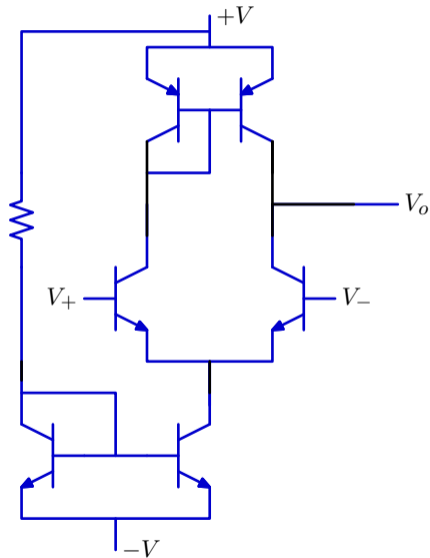
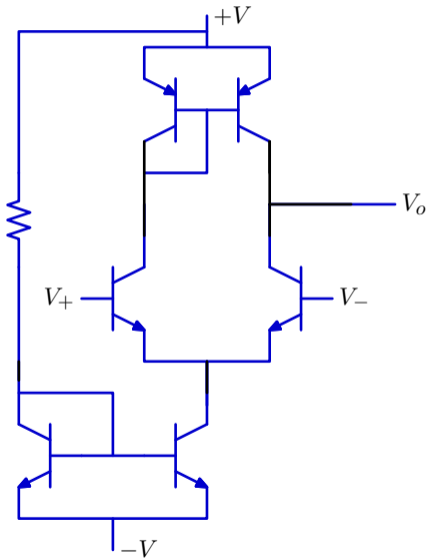
A pair of transistors can be used to split a current.



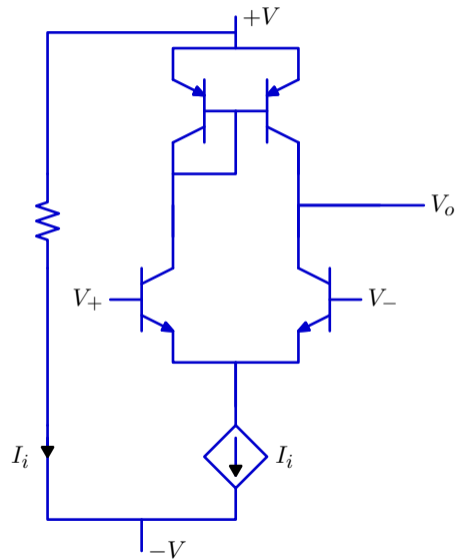
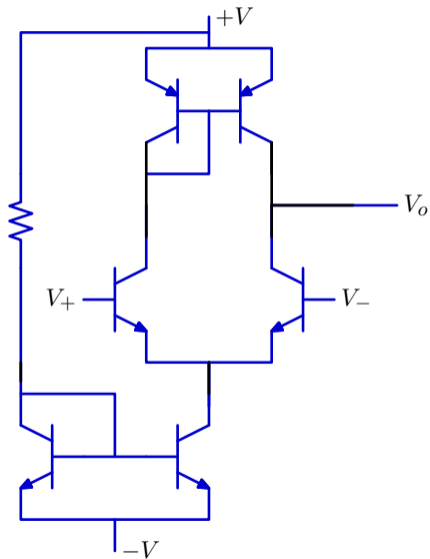
The fraction α is proportional to $e^{(V_+ - V_-)/v_T}$, where $v_T \approx 26\text{mV}$.

This “differential amplifier” can be represented by two voltage-controlled current sources.

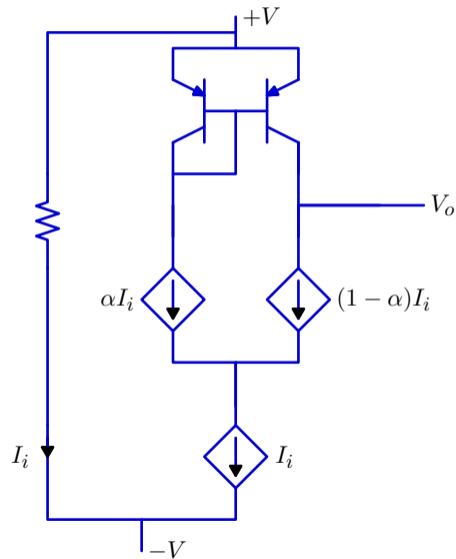
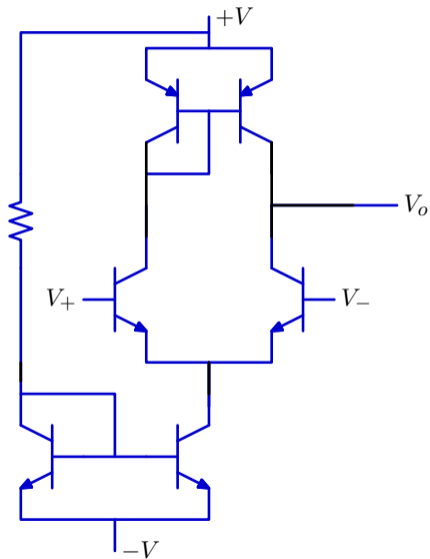
Modeling An Op-Amp



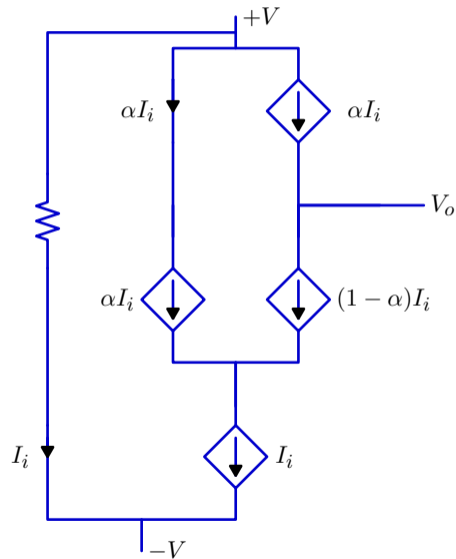
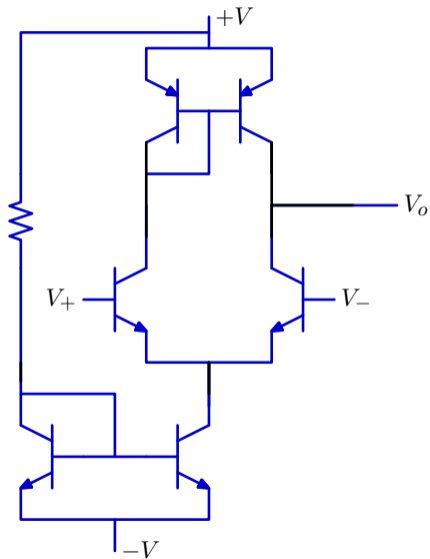
Modeling An Op-Amp



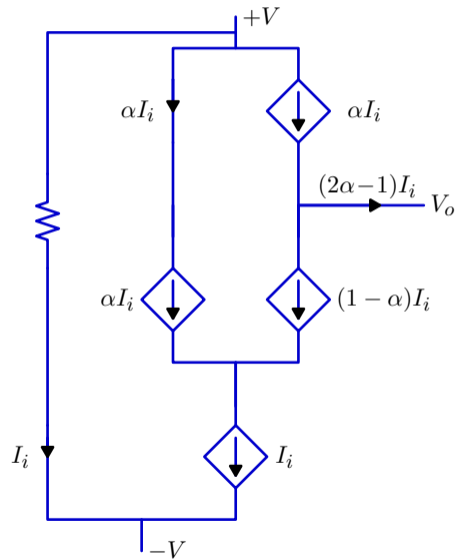
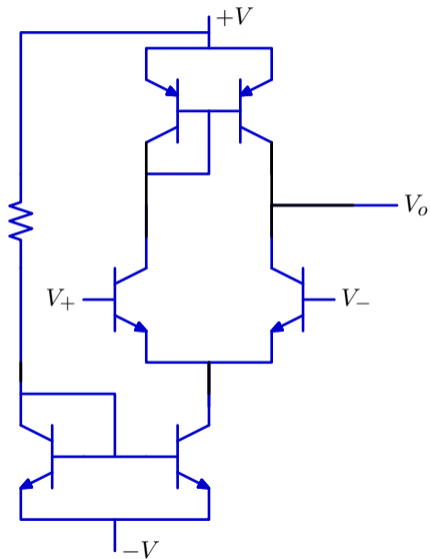
Modeling An Op-Amp



Modeling An Op-Amp

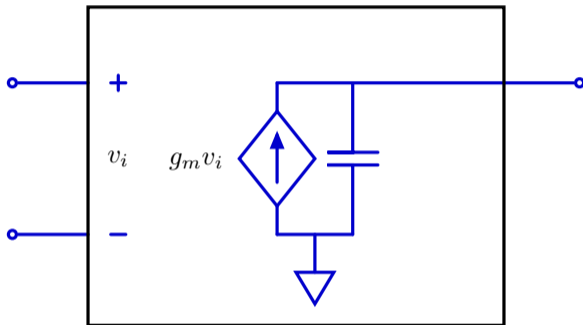


Modeling An Op-Amp



Modeling Time Dynamics

This leads us to a model of the op-amp that can explain the difference:



How does this circuit behave in the negative-feedback vs positive-feedback case?

Like we do with a lot of things, the important thing to remember is not this model, but the consequence of it: negative feedback drives the input potentials together (linear VCVS model applies!), positive feedback drives them apart.